

Two-wire Serial EEPROM

BM24C64B

Bestow Mascot

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<u>Description</u> BM24C64B

1. Description

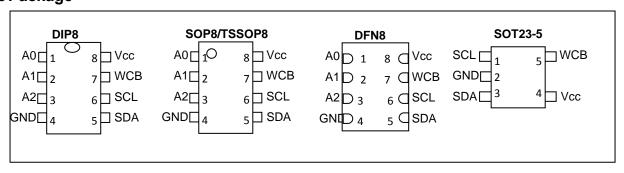
1.1 General Description

The BM24C64B is a 64-Kbit I²C-compatible Serial EEPROM (Electrically Erasable Programmable Read-Only Memory) device. It contains a memory array of 8192× 8 bits, which is 32-byte per page. The device is optimized for use in many industrial and commercial applications where low-power and low-voltage operation are essential. The BM24C64B is available in space-saving 8-lead DIP8/SOP8/TSSOP8 and DFN8 packages and is accessed via a two-wire serial interface.

1.2 Features:

- ➤ Single Supply Voltage and High Speed:1 MHz
- ➤ Operating Ambient Temperature: -40°C to +105°C
- > Schmitt Trigger, Filtered Inputs for Noise Suppression
- > Sequential & Random Read Features
- ➤ Write
 - ♦ Byte Write within 3 ms
 - ♦ Page Write within 3 ms
 - ♦ Partial Page Writes Allowed
- > Write Protect of the Whole Memory Array
- ➤ Self-timed Write Cycle
- > High Reliability
 - → Endurance: >1 Million Write Cycles
 - ♦ Data Retention: >100 Years

1.3 Package

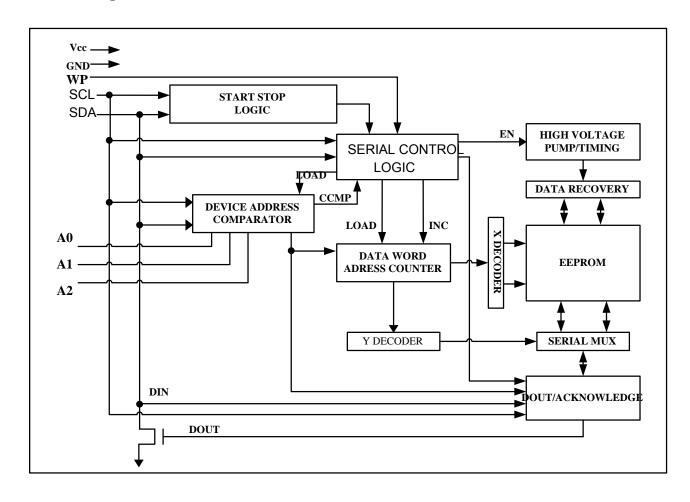


2. Pin Descriptions

Pin number	Designation	Name and Functions
		Device Addresses (A2, A1, A0): The A2, A1, and A0 pins are device
		address inputs. Typically, the A2, A1, and A0 pins are for hardware
1 – 3	A0 - A2	addressing and a total of 8 devices can be connected on a single bus
		system. If these pins are left floating, the A2, A1, and A0 pins will be
		internally pulled down to GND.
4	GND	Ground
		Serial Data (SDA): The SDA pin is bidirectional for serial data transfer.
5	SDA	This pin is open drain driven and may be wire-OR'ed with any number of
		other open-drain or open-collector devices.
6	SCL	Serial Clock (SCL): The SCL input is used to positive-edge clock data in
	JOL	and negative-edge clock data out of each device.
		Write Control (WCB): The Write Control input, when WCB is connected
7	WCB	directly to Vcc, all write operations to the memory are inhibited. When
,	WCB	connected to GND, allows normal write operations. If the pin is left
		floating, the WCB pin will be internally pulled down to GND.
8	Vcc	Power Supply

Block Diagram BM24C64B

3. Block Diagram



4. Functional Description

4.1 Device Operation

CLOCK and DATA TRANSITIONS: The SDA pin is normally pulled high with an external device. Data on the SDA pin may change only during SCL low time periods (see to Figure 1). Data changes during SCL high periods will indicate a start or stop condition as defined below.

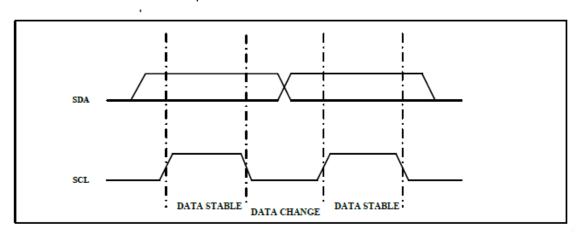


Figure 1 Data Validity

START CONDITION: A high-to-low transition of SDA with SCL high is a start condition which must precede any other command (see to Figure 2).

STOP CONDITION: A low-to-high transition of SDA with SCL high is a stop condition. After a read sequence, the stop command will place the EEPROM in a standby power mode (see Figure 2).

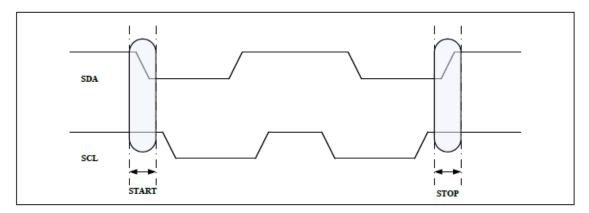


Figure 2 Start and Stop Definition

ACKNOWLEDGE: All addresses and data words are serially transmitted to and from the EEPROM in 8-bit words. The BM24C64B sends a "0" to acknowledge that it has received each word. This happens during the ninth clock cycle.

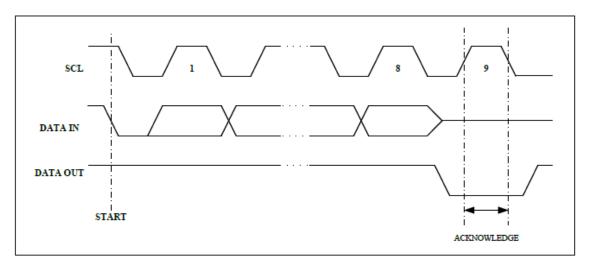


Figure3 Output Acknowledge

STANDBY MODE: The BM24C64B features a low-power standby mode which is enabled:

- (a) after a fresh power up,
- (b) after receiving a STOP bit in read mode,
- (c) after completing a self-time internal programming operation

MEMORY RESET: After an interruption in protocol, power loss or system reset, any two-wire part can be reset by following these steps: (a) Create a start condition, (b) Clock nine cycles, and (c) create another start bit followed by stop bit condition, as shown below. The device is ready for the next communication after the above steps have been completed.

4.2 Device Addressing

The BM24C64B require an 8-bit device address word following a start condition to enable the chip for a read or write operation (see table below).

Device Address

MSB							LSB
1	0	1	0	A2	A1	A0	R/W

The device address word consists of a mandatory "1", "0" sequence for the first four most significant bits.

The three A2, A1, and A0 device address bits allow as many as eight devices on the same bus. These bits must compare to their corresponding hardwired input pins.

The A2, A1, and A0 pins use an internal proprietary circuit that biases them to a logic low condition if the pins are floating.

The eighth bit of the device address is the read/write operation select bit. A read operation is initiated if this bit is high and a write operation is initiated if this bit is low. Upon a compare of the device address, the Chip will output a zero. If a compare is not made, the device will return to a standby state.

DATA SECURITY: The BM24C64B has a hardware data protection scheme that allows the user to write protect the entire memory when the WCB pin is at V_{CC}.

5. Instructions

5.1 Write Operations

BYTE WRITE: A write operation requires one 8-bit data word address following the device address word and acknowledgment. Upon receipt of this address, the BM24C64B will again respond with a "0" and then clock in the first 8-bit data word. Following receipt of the 8-bit data word, the BM24C64B will output a "0" and the addressing device, such as a microcontroller, must terminate the write sequence with a stop condition. At this time the EEPROM enters an internally timed write cycle, to the nonvolatile memory. All inputs are disabled during this write cycle and the EEPROM will not respond until the write is complete (see Figure 4).

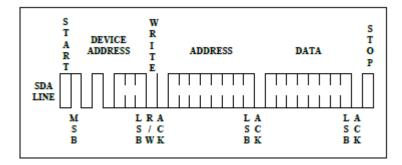


Figure 4 Byte Write

PAGE WRITE:

A page write is initiated the same as a byte write, but the microcontroller does not send a stop condition after the first data word is clocked in. Instead, after the EEPROM acknowledges receipt of the first data word, the microcontroller can transmit more data words. The EEPROM will respond with a "0" after each data word received.

The microcontroller must terminate the page write sequence with a stop condition (see Figure 5).

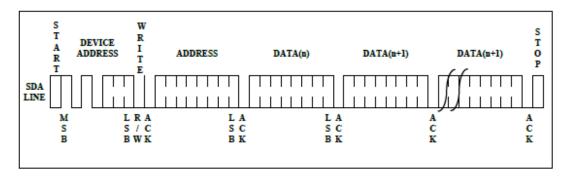


Figure 5 Page Write

The data word address lower six bits are internally incremented following the receipt of each data word.

The higher data word address bits are not incremented, retaining the memory page row location. When the word address, internally generated, reaches the page boundary, the following byte is placed at the beginning of the same page. If more than 32 data words are transmitted to the EEPROM, the data word address will "roll over" and previous data will be overwritten. The address roll-over during write is from the last byte of the current page to the first byte of the same page.

ACKNOWLEDGE POLLING: Once the internally timed write cycle has started and the EEPROM inputs are disabled, acknowledge polling can be initiated. This involves sending a start condition followed by the device address word. The read/write bit is representative of the operation desired. Only if the internal write cycle has completed will the EEPROM respond with a "0", allowing the read or write sequence to continue.

5.2 Read Operations

Read operations are initiated the same way as write operations with the exception that the read/write select bit in the device address word is set to "1". There are three read operations: current address read, random address read and sequential read.

CURRENT ADDRESS READ: The internal data word address counter maintains the last address accessed during the last read or write operation, incremented by one. This address stays valid between operations as long as the chip power is maintained. The address "roll over" during read is from the last byte of the last memory page to the first byte of the first page.

Once the device address with the read/write select bit set to "1" is clocked in and acknowledged by the EEPROM, the current address data word is serially clocked out. The microcontroller does not respond with an input "0" but does generate a following stop condition (see Figure 6).

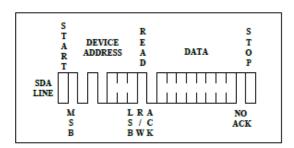


Figure6 Current Address Read

RANDOM READ: A random read requires a "dummy" byte write sequence to load in the data word address. Once the device address word and data word address are clocked in and acknowledged by the EEPROM, the microcontroller must generate another start condition. The microcontroller now initiates a Current Address Read by sending a device address with the read/write select bit high. The EEPROM acknowledges the device address and serially clocks out the data word. The microcontroller does not respond with a "0" but does generate a following stop condition (see Figure 7).

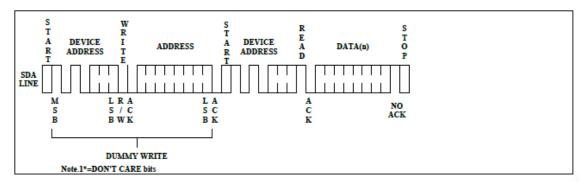


Figure7 Random Read

SEQUENTIAL READ: Sequential reads are initiated by either a current address read or a random address read. After the microcontroller receives a data word, it responds with an acknowledge. As long as the EEPROM receives an acknowledge, it will continue to increment the data word address and serially clock out sequential data words. When the memory address limit is reached, the data word address will "roll over" and the sequential read will continue. The sequential read operation is terminated when the microcontroller does not respond with a "0" but does generate a following stop condition (see Figure 8)

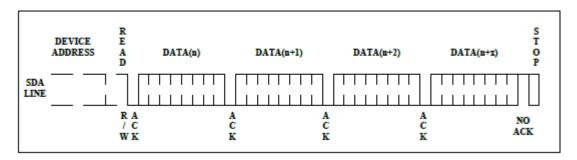


Figure8 Sequential Read

6. Electrical Characteristics

6.1 Absolute Maximum Stress Ratings

- ➤ Maximum Operation Voltage..... 6.5V
- ➤ Voltage on Any Pin with Respect to Ground.....-0.3V to (Vcc+0.3) V
- ➤ Operating Ambient Temperature-40°C to +105°C
- ➤ Storage Temperature.....-65°C to +150°C

Comments: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to this device. These are stress ratings only. Functional operation of this device at these or any other conditions above those indicated in the operational sections of this specification is not implied or intended. Exposure to the absolute maximum rating conditions for extended periods may affect device reliability.

6.2 Pin Capacitance

Symbol	Parameter	Max.	Units	Test Condition
Cı/o	Input/Output Capacitance (SDA)	8	pF	V _{I/O} =GND
Cin	Input Capacitance (A0,A1,A2,WCB,SCL)	6	pF	V _{IN} =GND

Note: Test Conditions: $T_A = 25$ °C, F = 1MHz, Vcc = 5.0V.

6.3 DC Electrical Characteristics

Symbol	Parameter	Min.	Тур.	Max.	Unit	Test Condition
lcc1	Supply Current	_	0.14	0.3	mA	Vcc=5.0V,
1001	очрру очисти	_	0.14	0.5	ША	Read at 400Khz
lcc2	Supply Current	_	0.28	0.5	mA	Vcc=5.0V
1002	Зарріу Сапені	_	0.20	0.5	шд	Write at 400Khz
I _{SB1}	Standby Current	_	0.03	0.5	uA	Vcc = 5.0V
1281	Standby Current	-	0.03	0.5	uA	$V_{IN} = V_{CC}$ or GND
lц	Input Leakage Current	-	0.10	1.0	μΑ	V _{IN} = V _{CC} or GND
lLO	Output Leakage Current	-	0.05	1.0	μΑ	Vout = Vcc or GND
VIL	Input Low Level	-0.3	-	0.3Vcc	V	-
ViH	Input High Level	0.7V _{CC}	-	V _{CC} +0.3	V	-
Vol1	Output Low Level	_	_	0.2	V	loL = 0.15mA
VOL1	$V_{CC} = 1.7V (SDA)$	_	_	0.2	V	IOL - 0.13111A
V _{OL2}	Output Low Level	_		0.4	V	I _{OL} = 3.0mA
V OL2	$V_{CC} = 5.0V (SDA)$	_	_	0.4	V	IOL - S.OTIA

Note: Unless otherwise specified, V_{CC} = 1.7V to 5.5V, T_A = -40°C to 105°C

6.4 AC Electrical Characteristics

Symbol	Parameter	1.7≤V _{CC} <2.5		2.	5≤V _{CC} ≤	5.5	Units	
Oyillboi	i didilictoi	Min.	Тур.	Max.	Min.	Тур.	Max.	Omics
fscL	Clock Frequency, SCL	-	-	400	-	-	1000	kHz
t _{LOW}	Clock Pulse Width Low	1.3	-	-	0.5	-	-	μs
tнідн	Clock Pulse Width High	0.6	-	-	0.26	-	-	μs
taa	Clock Low to Data Out Valid	-	-	0.9	-	-	0.45	μs
tı	Noise Suppression Time	-	-	0.05	-	-	0.05	μs
tBUF	Time the bus must be free before a new transmission can start	1.3	-	-	0.5	-	-	μs
thd.sta	Start Hold Time	0.6	-	-	0.25	-	-	μs
tsu.sta	Start Setup Time	0.6	-	-	0.25	-	-	μs
t _{HD.DAT}	Data In Hold Time	0	-	-	0	-	-	μs
tsu.dat	Data In Setup Time	0.1	-	-	0.1	-	-	μs
tR	Inputs Rise Time[1]	-	-	0.3	-	-	0.12	μs
tF	Inputs Fall Time[1]	-	-	0.3	-	-	0.12	μs
tsu.sто	Stop Setup Time	0.6	-	-	0.25	-	-	μs
tон	Data Out Hold Time	0.05	-	-	0.05	-	-	μs
twr	Write Cycle Time	ı	1.9	3	-	1.9	3	ms

Notes: Unless otherwise specified, V_{CC} =1.7V to 5.5V, T_A = -40°C to 105°C, C_L =100pF, Test Conditions are listed in Notes2.

- [1] This parameter is ensured by characterization not 100% tested
- [2] AC measurement conditions:
- ♦ R_L (connects to V_{CC}): 1.3k (2.5V, 5.5V), 10k (1.7V)
- ♦ Input pulse voltages: 0.3 Vcc to 0.7 Vcc
- ♦ Input rise and fall times: ≤50ns
- ♦ Input and output timing reference voltages: 0.5V_{CC}

6.5 Reliability Characteristic^[1]

Symbol	Parameter	Min.	Тур.	Max.	Unit
EDR ^[2]	Endurance	1,000,000	-	-	Write cycles
DRET	Data retention	100	-	-	Years

Note: [1] This parameter is ensured by characterization and is not 100% tested

[2] Under the condition: 25°C, 3.3V, Page mode

6.6 Bus Timing

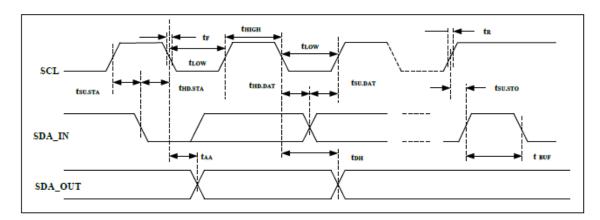
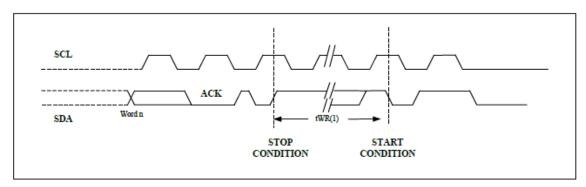


Figure9 Bus Timing

6.7 Write Cycle Timing

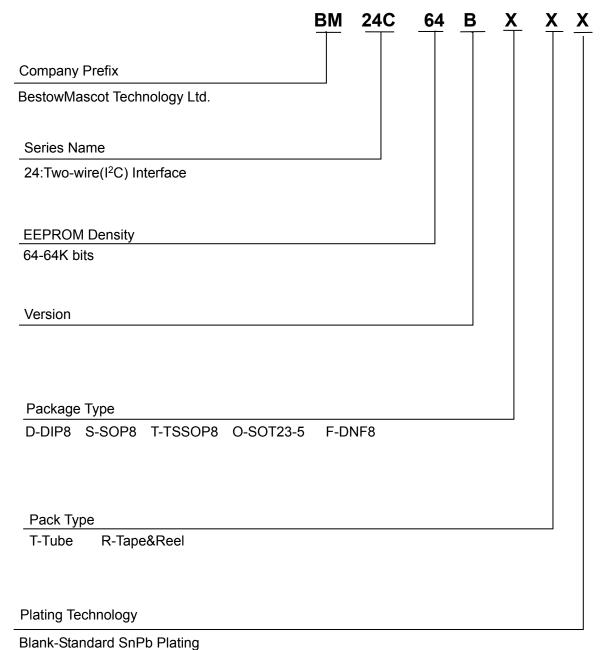


Note: The write cycle time tWR is the time from a valid stop condition of a write sequence to the end of the internal clear/write cycle.

Figure 10 Write Cycle Timing

7. Ordering Information

7.1 Naming Scheme



Model	DIP8	SOP8	TSSOP8	SOT23-5	DFN8
BM24C64B	V	V	V	V	V

√: Mass-produced

R-RoHS compliant

G-Green

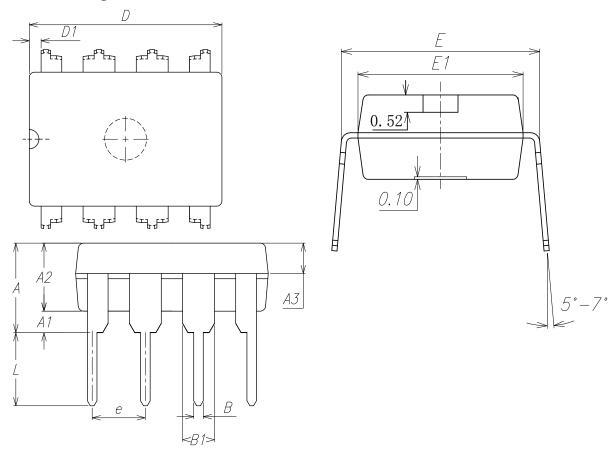
*: Design in

-: Be customize

7.2 Order Information

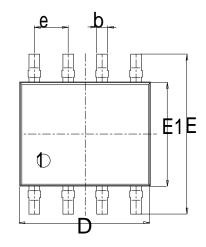
Package	Temperature Range	Vcc	HSF	Packaging	Order Code	
DIP8	-40℃-105℃	1.7V-5.5V	Green	Tube	BM24C64B-D-T-G	
SOP8	-40℃-105℃	1.7V-5.5V	Green	Tube	BM24C64B-S-T-G	
				0.00	Tape and Reel	BM24C64B-S-R-G
TSSOP8	-40℃-105℃	1.7V-5.5V	Green	Tube	BM24C64B-T-T-G	
100010	10 0 100 0		Croon	Tape and Reel	BM24C64B-T-R-G	
SOT23-5	-40℃-105℃	1.7V-5.5V	Green	Tape and Reel	BM24C64B-O-R-G	
DFN8	-40℃-105℃	1.7V-5.5V	Green	Tape and Reel	BM24C64B-F-R-G	

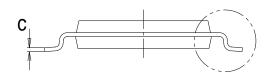
7.3 DIP8 Package Outline Dimensions

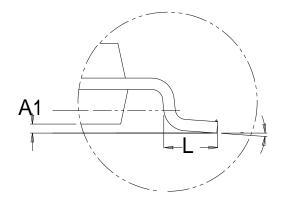


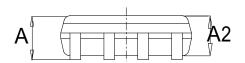
Cumbal	Dimensions	n Millimeters	Dimensions In Inches		
Symbol	Min	Max	Min	Max	
Α	3.60	4.00	0.142	0.157	
A1	0.51	-	0.020	-	
A2	3.10	3.50	0.122	0.138	
A3	1.50	1.70	0.059	0.067	
В	0.44	0.53	0.017	0.021	
B1	1.52	1.57	0.060	0.062	
D	9.20	9.25	0.362	0.364	
D1	0.561	0.611	0.022	0.024	
Е	7.63	7.68	0.300	0.302	
E1	6.35	6.40	0.250	0.252	
е	2.54	2.54BSC		BSC	
L	3.49	3.81	0.138	0.150	

7.4 SOP8 Package Outline Dimensions



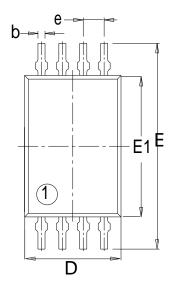


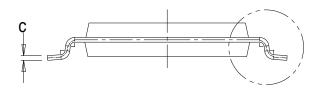


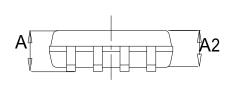


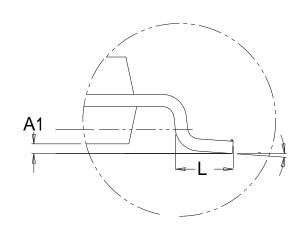
Symbol	Dimensions I	n Millimeters	Dimensions In Inches		
Symbol	Min	Max	Min	Max	
Α	1.350	1.650	0.053	0.065	
A1	0.100	0.250	0.004	0.010	
A2	1.450	1.525	0.057	0.060	
b	0.375	0.425	0.015	0.017	
С	0.245	(BSC)	0.010 (BSC)		
D	4.875	4.925	0.192	0.194	
E	5.900	6.100	0.232	0.240	
E1	3.825	3.925	0.151	0.155	
е	1.245	1.295	0.049	0.051	
L	0.615	0.765	0.024	0.030	
α	0°	5°	0°	5°	

7.5 TSSOP8 Package Outline Dimensions



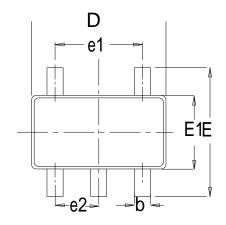


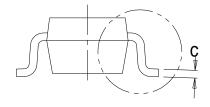


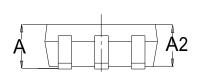


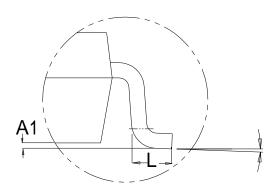
Comple of	Dimensions I	In Millimeters	Dimensions In Inches		
Symbol	Min	Max	Min	Max	
Α	0.850	1.100	0.033	0.043	
A1	0.070	0.130	0.003	0.005	
A2	0.850	0.900	0.033	0.035	
b	0.195	0.245	0.008	0.010	
С	0.127	(BSC)	0.005 (BSC)		
D	2.910	3.030	0.115	0.119	
E	6.230	6.480	0.245	0.255	
E1	4.370	4.430	0.172	0.174	
е	0.625	0.675	0.025	0.027	
L	0.562	0.638	0.022	0.025	
α	1°	7°	1°	7°	

7.6 SOT23-5 Package Outline Dimensions



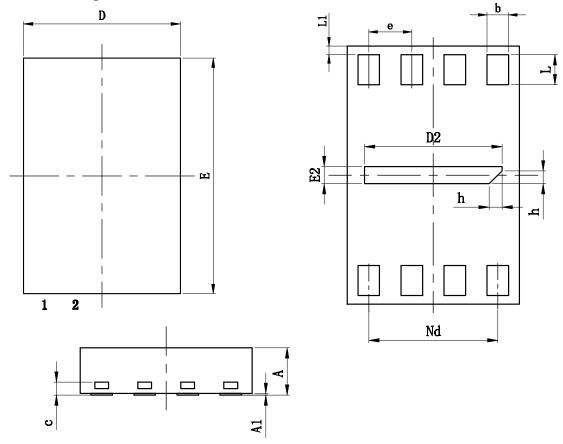






Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
А	1.050	1.250	0.041	0.049
A1	0.030	0.090	0.001	0.004
A2	1.050	1.150	0.041	0.045
b	0.350	(BSC)	0.014	(BSC)
С	0.152 (BSC)		0.006 (BSC)	
D	2.870	2.970	0.113	0.117
E	2.750	2.850	0.108	0.112
E1	1.550	1.650	0.061	0.065
e1	1.900 (BSC)		0.075 (BSC)	
e2	0.950 (BSC)		0.037 (BSC)	
L	0.350	0.450	0.014	0.018
α	0°	4°	0°	4°

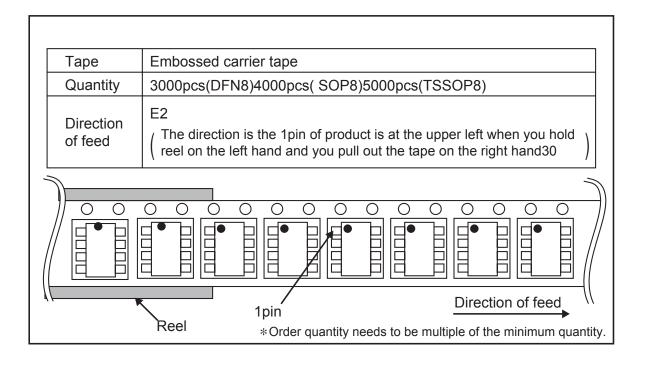
7.7 DFN8 Package Outline Dimensions



Symbol	Dimensions In Millimeters		Dimensions In Inch		
	Min	Max	Min	Max	
Α	0.500	0.600	0.020	0.024	
A1	-	0.050	-	0.002	
b	0.180	0.300	0.007	0.012	
С	0.100	0.200	0.004	0.008	
D	1.900	2.100	0.075	0.083	
D1	1.500	1.700	0.059	0.067	
е	0.500(BSC)		0.020(BSC)		
Nd	1.500(BSC)		0.059(BSC)		
E	2.900	3.100	0.114	0.122	
E2	0.100	0.300	0.004	0.012	
L	0.300	0.400	0.012	0.016	
L1	0.050	0.150	0.002	0.006	
h	0.050	0.250	0.002	0.010	

7.8 Tube and Reel Information

Container	Tube			
Quantity	2000pcs			
Direction of feed	Direction of products is fixed in a container tube			
*Order quantity needs to be multiple of the minimum quantity.				



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8. Notice

General Precaution

1) Before you use our Products, you are requested to carefully read this document and fully understand its contents. BM shall not be in any way responsible or liable for failure, malfunction or accident arising from the use of any BM's Products against warning, caution or note contained in this document.

2) All information contained in this document is current as of the issuing date and subject to change without any prior notice. Before purchasing or using BM's Products, please confirm the latest information with a BM sales representative.

Precaution on using BM Products

- 1) Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment, transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the BM sales representative in advance. Unless otherwise agreed in writing by BM in advance, BM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any BM's Products for Specific Applications.
- 2) BM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
 - [a] Installation of protection circuits or other protective devices to improve system safety
 - [b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure
- 3) Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, BM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any BM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
 - [a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
 - [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
 - [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl_2 , H_2S , NH_3 , SO_2 , and NO_2
 - [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
 - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
 - [f] Sealing or coating our Products with resin or other coating materials
 - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
 - [h] Use of the Products in places subject to dew condensation
- 4) The Products are not subject to radiation-proof design.
- 5) Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6) In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse) is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7) De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
- 8) Confirm that operation temperature is within the specified range described in the product

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specification.

9) BM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

Precaution for Mounting / Circuit board design

- 1) When a highly active halogen us (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2) In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the BM representative in advance. For details, please refer to BM Mounting specification

•Precautions Regarding Application Examples and External Circuits

- 1) If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
- 2) You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. BM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

Precaution for Electrostatic

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

• Precaution for Storage / Transportation

- 1) Product performance and soldered connections may deteriorate if the Products are stored in the places where:
 - [a] the Products are exposed to sea winds or corrosive gases, including Cl₂, H₂S, NH₃, SO₂, and NO₂
 - [b] the temperature or humidity exceeds those recommended by BM
 - [c] the Products are exposed to direct sunshine or condensation
 - [d] the Products are exposed to high Electrostatic
- 2) Even under BM recommended storage condition, solder ability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solder ability before using Products of which storage time is exceeding the recommended storage time period.
- 3) Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- 4) Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

Precaution for Product Label

QR code printed on BM Products label is for BM's internal use only.

Precaution for Disposition

When disposing Products please dispose them properly using an authorized industry waste company.

•Precaution for Foreign Exchange and Foreign Trade act

Since our Products might fall under controlled goods prescribed by the applicable foreign exchange and foreign trade act, please consult with BM representative in case of export.

Precaution Regarding Intellectual Property Rights

1) All information and data including but not limited to application example contained in this document is for reference only. BM does not warrant that foregoing information or data will not infringe any intellectual property rights or any other rights of any third party regarding such

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2) No license, expressly or implied, is granted hereby under any intellectual property rights or other rights of BM or any third parties with respect to the information contained in this document.

Other Precaution

- 1) The information contained in this document is provided on an "as is" basis and BM does not warrant that all information contained in this document is accurate and/or error-free. BM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties resulting from inaccuracy or errors of or concerning such information.
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- 3) The Products may not be disassembled, converted, modified, reproduced or otherwise changed without prior written consent of BM.
- 4) In no event shall you use in any way whatsoever the Products and the related technical information contained in the Products or this document for any military purposes, including but not limited to, the development of mass-destruction weapons.
- 5) The proper names of companies or products described in this document are trademarks or registered trademarks of BM, its affiliated companies or third parties.

Revision History BM24C64B

9. Revision History

Version	Publication Date	Pages	Revise Description
1.0	Apr.2017	23	Initial Document Release
1.0.1	Sep.2017	23	Revise Clerical Error of Naming Scheme
1.0.2	Jul.2018	23	Update Order Information
1.0.3	Apr.2019	23	Revise Byte Write Parameter